Effects of Dynamic Fragmentation on the Impact Force Exerted on Rigid Barrier: Centrifuge Modelling

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Effects of Dynamic Fragmentation on the Impact Force Exerted on Rigid Barrier: Centrifuge Modelling

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Abstract: Bi-dispersity is a prerequisite for grain-size segregation, which transports the largest particles to the flow front. These large and inertial particles can fragment upon impacting a barrier. The amount of fragmentation during impact strongly influences the force exerted on a rigid barrier. Centrifuge modelling was adopted to replicate the stresses for studying the effects of bi-dispersity in a granular assembly and dynamic fragmentation on the impact force exerted on a model rigid barrier. To study the effects of bi-dispersity, the ratio between the diameters of small and large particles (δ_s/δ_l), characterising the particle size distribution (PSD), was varied as 0.08, 0.26, and 0.56. The volume fraction of the large particles was kept constant. An δ_s/δ_l tending towards unity characterises inertial flow that exerts sharp impulses, and a diminishing δ_s/δ_l characterises the progressive attenuation of these sharp impulses by the small particles. Flows dominated by grain-contact stresses ($\delta_s/\delta_l < 0.26$), as characterised by the Savage Number, are effective at attenuating dispersive stresses of the large particles, which are responsible for reducing dynamic fragmentation. By contrast, flows dominated by grain-inertial stresses ($\delta_s/\delta_l > 0.26$) exhibit up to 66% more impulses and 4.3 times more fragmentation. Dynamic fragmentation of bi-disperse flows impacting a rigid barrier can dissipate about 30% of the total flow energy.

Key words: Bi-dispersity; dynamic fragmentation; impact; rigid barrier; centrifuge modelling

Introduction

Geophysical flows are stress-dependent phenomena, which surge downslope at high velocities and rapidly evolve from triggering to deposition (Cui et al. 2017). These flows consist of particles that cover a wide range of sizes, ranging from gravel to boulder. Bi-dispersity, two different particle sizes, is a prerequisite for grain-size segregation (Gray and Chugunov 2006), which transports large particles to the free surface and accumulates them at the flow front (Calvetti et al. 2000; Thornton et al. 2006). Grain-size segregation has been investigated in the context of the transportation (Zhou and Ng 2010) and deposition (Johnson et al. 2012) stages of mass-wasting processes. However, the effects of grain-size segregation on the impact forces exerted on rigid barriers (Lo 2000) remain a crucial scientific challenge. Large particles at the flow front can generate concentrated loads (Bowmen et al. 2010; Cui et al. 2018), which have been reported to severely damage reinforced-concrete structures situated in their flow paths (Zhang et al. 1996).

Aside from the concentrated loads that are exerted on rigid barriers, large particles can also fragment upon impact. The degree to which fragmentation occurs governs the resulting forces exerted on a barrier. One would expect that a particle that fragments would exhibit a smaller impact force compared to that of a particle that stays intact. Dynamic fragmentation is the reduction of the size of particles in rock avalanches and debris flows (Davies et al. 1999). This feature occurs when fast-moving particles grind or collide with each other, or with their boundaries (Bond 1952). Dynamic fragmentation has been evaluated against the runout distance for rock avalanches using centrifuge model tests (Bowman et al. 2012). These studies have proven that the centrifuge is a suitable tool for recreating the absolute stress state of a granular assembly (Schofield 1980; Taylor 1984; Bowman et al. 2010) and to generate stresses

that enable the investigation of dynamic fragmentation (Imre et al. 2010), which would otherwise not be possible using small-scale experiments (Davies and McSaveney 1999).

Bowman et al. (2012) demonstrated that the mobility of a rock avalanche is related to the relative breakage B_R of the flow material, as proposed by Hardin (1985) and given as follows:

$$B_R = \frac{B_T}{B_P} \quad (1)$$

where B_T is the total breakage, and B_P is the breakage potential. Both parameters are obtained from the PSDs of the geo-material. Breakage potential B_P is defined as the area bounded by the PSD before fragmentation, while total breakage B_T is defined by the area bounded between the PSDs before and after fragmentation. Breakage potential indicates the maximum breakage of particles that can occur by fragmentation, while total breakage represents the breakage that actually occurred.

Ng et al. (2017) focused on the fundamental impact mechanisms of granular flow and viscous flow on a model rigid and flexible barriers (Ng et al. 2016b) using the geotechnical centrifuge. In essence, a frictional sand material with a low degree of viscous shearing was compared to viscous fluid. Both of these flows were assumed to behave as a continuum with absence of large particles or inclusions. The study reported in Song et al. (2018) was a continuation of the previous studies to examine the effects of solid fraction on two-phase debris flows, sand and viscous fluid, impacting a rigid barrier. Furthermore, Song et al. (2018) examined the effects of particle size of dry granular flow impacting a rigid barrier. This study improved the characterisation between flow that behaves as a continuum and flow that behaves

discretely during impact. These findings help to discern when a design should be continuum-based (hydrodynamic approach) or discrete based (Hertz equation).

Back-analyses of nine field cases by Locat et al. (2006) show that fragmentation energy represents about 20% of the initial potential energy of a geophysical flow. Furthermore, findings show that the effects of dynamic fragmentation are augmented at the front of geophysical flows where large and inertial particles collide with each other as they travel downslope.

Although studies have been carried out to investigate the effects of dynamic fragmentation during transportation, there remains a knowledge gap on the effects of dynamic fragmentation on the impact force exerted on a barrier. Significant dynamic fragmentation was observed in the centrifuge tests conducted by Song (2017) and Song et al. (2018). However, the effects of dynamic fragmentation on the impact force exerted on the model rigid barrier was not examined. Clearly, the contrasting effects of sharp impulses induced by large particles on a rigid barrier and the dynamic fragmentation of these particles, which dissipate energy, influence the resisting force required by a rigid barrier. These pertinent features are important in the design of a rigid barrier and warrant further investigation.

In this paper, a series of centrifuge experiments were carried out. The experiments were designed to study the effects of bi-dispersity and dynamic fragmentation on the impact force exerted on a model rigid barrier. The size of the small particles was varied, while both the size of the large particles and the volume ratio between small and large particles were held constant. The novelty of this study lies in focusing on the degree of dynamic fragmentation after granular flows impact a rigid barrier. The scientific challenges pertaining to what flow

compositions are most prone to dynamic fragmentation and the loading response on a rigid barrier are investigated.

Limitations of hydrodynamic impact model for rigid barriers

The current deficiency in our understanding of the impact force exerted on barriers is reflected by international guidelines (VanDine 1996; Proske et al. 2011; Kwan 2012). Generally, an estimate of the impact forces of geophysical flows is assumed to be dominated by the dynamic forces. A generalised form of hydrodynamic equation (Hung et al. 1984; WSL 2009; Kwan 2012; Bugnion et al. 2010; Bugnion et al. 2012), which assumes the momentum upon impact is destroyed, on a rigid barrier is given as follows:

$$F = \alpha \rho v^2 h w \quad (2)$$

where F is the impact force, α is the dynamic pressure coefficient, ρ is the debris density, v is the flow velocity, h is the flow thickness and w is the channel width. The main limitation of the hydrodynamic equation is that the flow is assumed as an equivalent fluid. This means that the effects of particle size and dynamic fragmentation are not explicitly considered. The assumption that momentum is completely destroyed upon impact in Eqn. 2 is not appropriate for discrete particles impacting a barrier. This is because the impact force will obviously be augmented when the particles rebound off of the barrier. Therefore α is used to empirically compensate for this uncertainty in the flow composition. The deficiency in the hydrodynamic approach in predicting the impact force when large boulders are included in the flow is best documented by Zhang (1993). In the Jiangjia Ravine of China, back-calculated α values from 70 measurements are ranged from 3 to 5. The variability is attributed to the inclusion of entrained boulders in the flows. Volkwein (2014) further emphasized that α is dependent on

the flow composition. More specifically, for granular debris flows (1900 to 2300 kg/m³), the α value should be 2 while for fluid-like debris flows (1600 to 2000 kg/m³) the α value ranges from 0.7 to 1.0. The higher solid fractions in granular debris flows entail higher dynamic pressure coefficients compared to fluid-like flows with lower solid fractions. The large particles are also likely to rebound upon impacting a rigid structure, and therefore augmenting the impact force (Jiang and Towhata 2013). Evidently, recommendations for α value are inconsistent and physical data is urgently required to elucidate the effects of particle size.

To capture the impact of boulders or a large and hard inclusion, the Hertz equation is often used to estimate the impact force. A modified version of the Hertz equation for a granite boulder impacting a reinforced concrete wall (Kwan 2012) is given as follows:

$$F = K_c 4000 v^{1.2} R^2 \quad (3)$$

where K_c is the load reduction factor and R is the boulder radius. The load-reduction factor K_c is empirically recommended as 0.1. This value is for a perfectly elastic impact scenario, which is reduced by 90% to account for a plastic deformation during impact. The validity of the Hertz equation when more than a single particle impact a rigid barrier is a crucial scientific challenge that needs to be addressed.

Centrifuge modelling

The geotechnical centrifuge at The Hong Kong University of Science and Technology (Ng 2014) was used to carry out the experiments in this study. The centrifuge has a diameter of 8.4 m and a payload capacity of 400 g-ton. The tests were carried out at a g-level of 22.4. Details of the model setup, instrumentation, test programme and test procedures are described below.

Scaling and flow characterisation

Details of scaling principles are discussed in Chikatamarla et al. (2006). The downslope motion of a geophysical flow is driven by gravitational potential, therefore the velocity scale v is characterised using $(gL)^{1/2}$ (Iverson 1997; Valentino et al. 2008), where L is the characteristic flow length. In centrifuge modelling, as the gravitational acceleration increases N times, both the linear scale and inertial time scale are reduced by N times, thereby resulting in a scale factor of unity for the flow velocity. Based on the fundamental principles of centrifuge modelling, the impact pressure ($P \sim \rho v^2$) is the same as that of the prototype. The impact force ($F \sim \rho v^2 A$) induced on the barrier has a scale factor of $1/N^2$, where A is the impact area on the barrier (Ng et al. 2017). According to Hertz contact theory, the boulder impact force F also has a scale factor of $1/N^2$. A summary of relevant scaling laws is given in Table 1.

The collisional regime of the flow can be described by kinetic theory. The kinetic energy dissipates differently depending on collisions within the granular medium (Azanza et al. 1999). To quantify the collisions among grains within the flow, the relative importance of inertial and contact grain stresses can be assessed using the Savage Number (Savage 1984). This dimensionless group is used to characterise the mesoscopic stresses of the granular assembly and correlate with the degree of dynamic fragmentation and the force exerted on the rigid barrier. The Savage Number is given as follows:

$$N_{\text{Sav}} = \frac{\delta^2 \dot{\gamma}^2}{gh} \quad (4)$$

where δ is the grain diameter and $\dot{\gamma}$ is the shear strain rate. The Savage Number can characterise whether flows are frictional or contact-dominated.

$$\dot{\gamma} = \frac{v_s - v_b}{h} \quad (5)$$

where v_s is the flow velocity at the surface and v_b is flow velocity at the base. The empirical threshold between the two regimes is reported as $N_{\text{Sav}} = 0.1$ (Savage and Hutter 1989). A summary of the parameters used to calculate N_{Sav} is given in Table 2.

Model setup and instrumentation

Figure 1 shows the model setup used in this study. A side view of the model container, with dimensions of 1245 mm in length, 350 mm in width, and 850 mm in depth, on the centrifuge platform is shown in Fig. 1a. This container has a Perspex window for capturing the flow kinematics of the tests. A model slope with an incline of 25° was installed in the model container. A storage container with a volume of 0.03 m^3 was mounted above the upstream end of the model slope. A hinged-door at the bottom of the storage container was used to retain the source material. This door was controlled using a hydraulic actuator to release the source material on to the channel in-flight.

A magnesium alloy plate, 200 mm in height and 233 mm in width, was installed perpendicularly to the channel to model a rigid barrier (Fig. 1b). The Young's modulus of the magnesium alloy plate is the upper limit of that of reinforced concrete. A through-hole compression load cell was installed between an alloy plate and aluminum buttress to measure the total load on the model rigid barrier. A sampling rate of 20 kHz was selected to ensure the details of the dynamic process were captured. As a single load cell was used to measure the total load acting on the barrier. This means that spikes are likely occurring at different locations along the barrier. Since the barrier is not cantilevered and meant to measure load one-dimensionally (slope parallel direction), details pertaining to the load distribution and

implications on the induced bending moment could not be interpreted. A high-speed camera, with a sampling rate of 640 frames per second at a resolution of 1300×1600 pixels was used to record the impact kinematics. High-speed images enabled particle imagery velocimetry (PIV) for analysing the velocity fields during impact (White et al. 2003).

Test programme

To investigate the effects of bi-dispersity and dynamic fragmentation on the impact force exerted on a model rigid barrier, both control and impact tests were carried out. Prior to impact tests, control tests, without a barrier, were used to characterise the flow dynamics.

The model size of the small particles forming the bi-disperse flows, was varied as 3 mm (67 mm in prototype), 10 mm (224 mm in prototype) and 22 mm (462 mm in prototype) while the size of the large particles remained unchanged as 39 mm (874 mm in prototype) (Fig. 2). A summary of the test programme is given in Table 2. The volume fraction of large particle (39 mm) to small particles (22 mm, 10 mm and 3 mm) was selected as 3 : 7. Casagli et al. (2003) summarised 42 granular flows from field study. The boulder inclusion of the granular flows was ranged from 10% to 60% of the total grains. High volume fraction of large particles would dominate the effects of bi-dispersity on dynamic fragmentation. After consideration of achieving research purposes, 30% of large particles was selected to model bi-disperse flows in this study. 0.874 mm, 462 mm, 224 mm and 67 mm grains are classified as large boulders, boulders, cobbles and coarse gravels (Bell 2013). To characterise the PSDs of these bi-disperse flows, the diameter of the small particles was normalised by the diameter of the large particles (δ_s/δ_l). To some extent, the large particles represent the boulders that are often entrained and transported to the front of a flow. A δ_s/δ_l value of zero represents mono-disperse flows comprising only large particles, whereas a δ_s/δ_l of unity represents mono-disperse flows

comprising particles of the same size. For a constant volume ratio between the small and large particles, a vanishing δ_s/δ_l can be expected that the flow to be dominated by contact stresses. By contrast, for a δ_s/δ_l of unity, one can expect the flow to be dominated by inertial stresses. The impact force exerted by flows that are highly inertial tends to induce sharp impulses, whereas the impact force exerted by flows that are highly contact-dominated tends to dissipate flow kinetic energy rapidly and does not exhibit sharp impulses (Song et al. 2018).

Test procedures

A model volume of 0.027 m³ of source material was prepared in the storage container, at 22.4 g this volume is equivalent to 170 m³ in prototype. The samples were initially prepared to reach a target bulk density of 1300 kg/m³ by firstly layering the large particles near the base of the container, followed by the small particles. The centrifuge was spun to the target g-level of 22.4. Afterwards, the hinged-door was released by activating the hydraulic actuator used to secure the door. The source material was mobilised on to the slope and flowed into the model rigid barrier. Simultaneously, the data logger and high-speed cameras were obtained measurements. After each test, the glass fragments inside the centrifuge model container were collected. The fragments were then sorted using sieve analysis and weighed using an electronic balance. The size and mass of fragmented glass spheres were recorded to quantify the degree of dynamic fragmentation. PSDs before and after each test were obtained.

Interpretation of test results

Observed impact kinematics

The impact kinematics are shown for bi-disperse flows with normalised particle diameters of $\delta_s/\delta_l = 0.08$ and 0.56 in Figs. 3 and 4, respectively. The difference between these two flows lies in the size of the small particles comprising the flow. The volume ratio between the small and

large particles remains constant as 7:3. Snapshots from the high-speed camera are shown on the left and the corresponding PIV analysis is shown on the right. The impact time is normalised as unity ($t = 1.00$ s) just as the flow front reaches the model rigid barrier.

Visualisations were made based on high-speed imagery and using PIV analysis (White et al. 2003). Traces of glass fragments in high-speed images were observed visually. The collisional processes were quite chaotic and the corresponding PIV vectors do not behave in a systematic manner. Figure 3 shows the impact kinematics of the bi-disperse flow with a normalised particle diameter of $\delta_s/\delta_l = 0.08$. The flow front impacts the barrier at $t = 1.00$ s (Fig. 3a). At $t = 1.67$ s, dynamic fragmentation of the large particles is observed and the small particles runup along the vertical face of the model rigid barrier (Fig. 3b). This runup is corroborated by the vertical vectors observed in the corresponding PIV analysis. Also, the accumulation of the large particles at the front and free surface of the flow, via kinetic sieving, is observed. At $t = 2.43$ s, the small particles cascade over the barrier and deposition forms at the barrier. High-speed images showed deposited material in front of the barrier, which was corroborated with near static vectors from PIV. Vectors near the top of the barrier correspond with particles cascading over the barrier (Fig. 3c). At $t = 3.02$ s, the size of the deposited material at the base has increased and only a thin layer of granular material flows over the surface of the deposited material (Fig. 3d).

Observations were also made based on high-speed imagery and PIV. Figure 4 shows the impact kinematics of the flow with a normalised particle diameter of $\delta_s/\delta_l = 0.56$. Similar to the impact kinematics observed for $\delta_s/\delta_l = 0.08$, the flow front approaches and impacts the barrier at $t = 1.00$ s (Fig. 4a). A more inertial flow front, compared to $\delta_s/\delta_l = 0.08$, embedded with fragments is observed. More obvious fragmentation has occurred and is attributed to the

collisional stresses of the large particles colliding at the front of the flow. The corresponding PIV vectors are less coherent as more dynamic fragmentation occurs. After the flow impacts the barrier at $t = 1.67$ s (Fig. 4b), fragments are observed at the interface between the flow and the barrier. At $t = 2.34$ s, more fragments are observed at the interface between the flow and the barrier (Fig. 4c). Simultaneously, the deposited material is observed at the base of the barrier. The collisional nature of the flow remains obvious near the free-surface and no significant overflow is observed. At $t = 3.02$ s (Fig. 4d), the impact process begins to reach static condition and only a thin layer of flow is observed on top of the deposited material.

Influence of particle size

Figure 5 show a comparison of the force time-histories for bi-disperse flows with normalised particle diameters of $\delta_s/\delta_l = 0.08$ (Fig. 5a), 0.26 (Fig. 5b), and 0.56 (Fig. 5c). The dynamic loads are normalised with the static load for each test. The time is unity ($t = 1.00$ s) when the flow front reaches the model rigid barrier. The estimated load using the hydrodynamic equation (Eqn. 2) with an α value of 2.5 (Kwan 2012) and the Hertz equation (Eqn. 3) with a K_c value of 0.1 (Kwan 2012), and the superposition of Eqns. 2 and 3 are shown for reference.

For $\delta_s/\delta_l = 0.08$, numerous sharp impulses are generated when the flow impacts the rigid barrier (Fig. 5a). The peak impulse is greater than the load estimated using the Hertz equation and the hydrodynamic equation by more than five times and 13%, respectively. The impulses eventually diminish as the impact process reaches a static state. The superposition of both Eqns. 2 and 3 successfully bounds the measured peak load. To highlight the uniqueness of the impact behaviour of bi-disperse flows, the impact behaviour of dry Leighton Buzzard (LB) Fraction C sand and a two-phase mixture tests, with 50% solid fraction of LB Fraction C sand (Song et al. 2018), are shown for comparison. Dry LB Fraction C sand exhibits a continuous and

progressive loading pattern towards a static state without an obvious dynamic peak or sharp impulses. This observed behaviour is similar to that of the loading pattern reported for low-discharge granular flow tests by Ashwood and Hungr (2016). Also, the tapered shape of the flow front is instrumental to the development of the progressive loading behaviour. The two-phase mixture, however, exhibits a distinct peak load before a static state. The two-phase mixture is fluidised so that it takes a longer time to reach a static condition. The dry sand and two-phase mixture tests conducted by Ng et al. (2017) and Song et al. (2018) are bounded by the superposition of both Eqns. 2 and 3. However, the bi-disperse flows with hard and large inclusions cannot be bounded by existing guidelines. These results suggest that the entrainment of large and hard inclusions in a geophysical flow warrants a careful consideration in the design of rigid barriers.

Similarly, for bi-disperse flow with a normalised particle diameter of $\delta_s/\delta_l = 0.26$ (Fig. 5b), a multitude of sharp impulses are generated upon impact. These impulses eventually diminish towards a static state. However, the peak impulse exceeds the superposition of Eqns. 2 and 3 by about 9%. Results show that the number of impulses generated for bi-disperse flows with normalised particle diameter $\delta_s/\delta_l = 0.26$ are greater than that for normalised particle diameter of $\delta_s/\delta_l = 0.08$. The more effective attenuation of impulses for $\delta_s/\delta_l = 0.08$ is due to more enduring contacts between the small particles, which are more effective at dissipating energy through friction. Similarly, for the bi-disperse flow with normalised particle diameter $\delta_s/\delta_l = 0.56$ (Fig. 5c), similar sharp impulses are generated. However, there are significantly more impulses compared to that observed in Figs. 5a and 5b. More specifically, 66% more impulses are counted when the normalised particle diameter δ_s/δ_l is increased from 0.08 to 0.56. The impulses from $\delta_s/\delta_l = 0.56$ also exceed the superposition of Eqns. 2 and 3 by as much as 48%. Clearly, the inclusion of large particles and the relative size of the finer particles strongly

influence the impact force on a rigid barrier and the use of existing guidelines warrants careful consideration.

A comparison of the force time-histories shows that as δ_s/δ_l of the bi-disperse flows is reduced, the flows are more effective at attenuating sharp impulses induced on the rigid barrier. This observation implies that small particles in a bi-disperse mixture play a significant role in cushioning the dispersive stresses of the large particles. A comparison with existing impact models corroborates that the Hertz equation, which assumes a single sphere impacting a flat surface cannot holistically predict the impact of a cluster of large particles impacting a rigid barrier. The hydrodynamic equation also does not appear to consistently be able to sufficiently bound the sharp impulses from the bi-disperse mixture in this study (Figs. 5b and 5c), even with a dynamic pressure coefficient of 2.5. This indicates that the discrete nature of flows with large particles tends to generate impulse that cannot be captured by the concept of an equivalent fluid (Hung 1995) as implicitly assumed in Eqn. 2.

The results show the peak loads exerting on rigid barrier with the presence of discrete boulders within the flow. The superposition of the hydrodynamic equation and Hertz equation (Kwan 2012) is not sufficient to bound the measured impact loads in this study (Fig. 5). This implies that the existence of entrained boulders may require either the dynamic pressure coefficient α or the load reduction factor K_c to be modified to ensure a robust barrier design.

Influence of grain stresses on impact force

The influence of grain stresses, manifested in the N_{sav} on the back-calculated α is shown in Fig. 6. The α values are back-calculated using the peak loads measured from each test. Reference lines are provided to indicate α values from different literatures. More particularly, α values

are recommended by Zhang (1993) and Volkwein (2014). The N_{Sav} itself relies on a characteristic diameter, which is taken as the mean particle size based on the volume fraction in this study. Results show that as the flow becomes more inertial, or as the particle size ratio increases, α also increases. Results indicate that the hydrodynamic approach, which relies on a single α value, is not appropriate for capturing the effects of particle size for rigid barrier. The recommended value of α as proposed by Zhang (1993) can capture the short duration impulses exerted by large particles in bi-disperse flows. This is likely due to the prevalence of large boulders reported in the Jiangjia Ravine, which is reflected in the back-calculated α values. Findings also suggest that recommended α values are likely dependent on the prevailing geological settings and whether large clasts were present.

Potential implications to barrier design

The results in this study show that the recommended dynamic pressure coefficient in current design guidelines (Kwan 2012) is not sufficient to capture flows with large and hard inclusions. Evidently, a larger dynamic pressure coefficient is required (at least 5 for particle diameters up to 874 mm based on the results of this study). A cluster of large particles possess extremely high momentum, thereby resulting in high impact loads. To account for such induced loads, comprehensive boulder surveys are necessary for mitigation strategies before designing barriers. Also, installation of cushioning material is clearly an important feature for rigid barriers. Cushioning materials should no longer be prescriptive since they have been reported to attenuate impact loads by up to 89% (Ng et al. 2016a; Lam et al. 2018).

Dynamic fragmentation

Dynamic fragmentation occurs when grains grind, crush and collide with each other (Bond 1952). In this study, dynamic fragmentation may occur during any of the three stages. First,

when the flow is released from the storage container, dynamic fragmentation may occur as the flow impacts at the base of the channel. Second, as particles experience crushing, grinding, and collisions before the flow impacts the model rigid barrier. Third, during impact against the model rigid barrier. A summary of the fragmentation measurements is given in Table 3. The percentage of dynamic fragmentation for small particles in the bi-disperse flows is from 0.2% to 1.1%, while dynamic fragmentation for large particles is from 3.5% to 12.5%. Measurements indicate that fragmentation predominantly occurs for large particles, which are more inertial (Fig. 6).

Figure 7 shows PSDs before and after each test for bi-disperse flows with normalised particle diameters of $\delta_s/\delta_l = 0.08, 0.26, \text{ and } 0.56$. To study the effects of fragmentation that occurs when the granular material impacts the channel, relevant tests on a flexible barrier were repeated. The purpose of the flexible barrier is to quantify the effect of dynamic fragmentation resulting from impact. Song et al. (2018) reported that flexible barriers are very effective at attenuated sharp impulses and thus the dynamic fragmentation during impact. These flexible barrier tests serve merely as a reference in an effort to isolate the effects of dynamic fragmentation during impact upon barriers. Although not the focus of this study, details of the flexible barrier are discussed in Ng et al. (2016b).

Figure 7a shows a comparison of the PSDs for the bi-dispersed flow with a normalised particle diameter $\delta_s/\delta_l = 0.08$ before and after the test for barriers. Results indicate that dynamic fragmentation is predominantly from the large particles. This is because the small particles act as a cushioning medium for the larger particles. The cushioning medium effectively attenuates flow kinetic energy through enduring frictional-contact stresses. The cushioning effect results in less impulses than that of the flows with larger particle diameter ratios. Figure 7b shows a

comparison of the PSDs for the bi-disperse flow with a normalised particle diameter of $\delta_s/\delta_l = 0.26$ before and after the test for barriers. Results show a more dynamic fragmentation of both the small and large particles compared to that in Fig. 7a, where the size of the small particles is about three times smaller than that presented in Fig. 7b. The higher degree of dynamic fragmentation is caused by the increase in particle diameter of the small particles comprising the bi-disperse flows. The less effective cushioning medium increase the degree of dynamic fragmentation of the large particles. Figure 7c shows a comparison of the PSDs for the bi-disperse flow with a normalised particle diameter of $\delta_s/\delta_l = 0.56$ before and after the test for barriers. The degree of dynamic fragmentation reveals a much wider range of fragment size than both Figs. 7a and 7b. The more inertial the flow is, the higher the resulting impact force exerted on a rigid barrier, and therefore a higher degree of dynamic fragmentation. The relative breakage is calculated increased in about 4 times when normalised particle diameter δ_s/δ_l is increased from 0.08 to 0.56.

Comparisons of the PSDs are also shown for the bi-dispersed flow after the test for a model flexible barrier in each figure. Similar to tests of rigid barrier, more dynamic fragmentation is found with increase in normalised particle diameter δ_s/δ_l . Effects of bi-dispersity can also be observed for tests for tests with flexible barrier. However, by comparing the same normalised particle diameter, the corresponding relative breakage is greatly reduced. The reduction in relative breakage is due to the absence of dynamic fragmentation during impact on a highly-deformable flexible barrier. The influence from distinguished barriers is further discussed in Figure 8.

Figure 8 shows the effects of grain stresses, manifested in the N_{sav} , on the degree of dynamic fragmentation using relative breakage B_R (Eqn. 1) as a benchmark. Relative breakage

B_R , representing degree of dynamic fragmentation increases with N_{Sav} . Although, dynamic fragmentation clearly occurred as the flow impacts the rigid barrier, there were also fragments embedded in the flow before impacting the model rigid barrier. A more systematic investigation is required to consider the stage at which the particles begin to fragment. Notwithstanding, this study shows that dynamic fragmentation from impact is a very significant contributor to the dissipation of total energy. Results show that the grain stresses in the flow, specifically N_{Sav} , is directly related to relative breakage B_R . Higher grain inertial stress, and therefore higher N_{Sav} , results in a higher degree of dynamic fragmentation. The measured relative breakage for a model flexible barrier is reduced up to 74% for normalised particle diameter δ_s/δ_l of 0.26 compared to that measured for a model rigid barrier.

Two references are shown for rock avalanches in Ashburton, New Zealand (McSaveney et al. 2000) and in La Madeleine, France (Locat et al. 2006). One would expect that the degree of dynamic fragmentation should be more significant for rock avalanches undergoing long transportation distances compared to the shorter transportation distances travelled by the model flows in this study. However, the bi-disperse flows with a normalised particle diameter of $\delta_s/\delta_l = 0.56$ reveals a relative breakage of about 0.28. This value suggests that despite the short transportation distance in the centrifuge test, the degree of dynamic fragmentation predominantly resulted from either the impact of flow material onto the channel base or from impact on the model rigid barrier.

Figure 9 shows a comparison of the estimated fragmentation energy E_F with relative breakage B_R in this study. The fragmentation energy E_F of the bi-disperse flows is calculated by considering the potential energy, kinetic energy and frictional energy of the flow, as characterised by Heim (1932). Based on the interpretation of nine field rock avalanches, about

20% of the potential energy is converted to fragmentation energy (Locat et al. 2006). Findings also suggest that despite the short transportation length in this study, the degree of dynamic fragmentation for bi-disperse flows with normalised particle diameters of $\delta_s/\delta_l = 0.26$ and $\delta_s/\delta_l = 0.56$, exhibit more than 20% in energy dissipation via fragmentation. The calculated fragmentation energy E_F of $\delta_s/\delta_l = 0.56$ is even up to 31%. This indicates that dynamic fragmentation from impact may be more significant compared to dynamic fragmentation that occurs during transportation. Notwithstanding, a comparison between Figs. 6 and 8 support that the cushioning effect resulting from bi-dispersity is more effective at attenuating sharp impulses compared to dynamic fragmentation during impact. The back-calculated fragmentation energy E_F from flows impacting a model flexible barrier shows a decrease in relative breakage up to 49% for normalised particle diameter $\delta_s/\delta_l = 0.26$. The flexibility of the barrier is very effective at attenuating the impact force and therefore reduces dynamic fragmentation upon impact. Correspondingly, the fragmentation energy is also reduced.

Conclusions

A series of centrifuge tests were carried out to investigate the effects of bi-dispersity and dynamic fragmentation on the impact force exerted on a model rigid barrier. The ratio of small to large particles, and the diameter of the large particles were held constant, while the diameter of small particles was varied. Findings from this study are drawn as follows:

- a) Normalised particle diameter δ_s/δ_l governs the collisional regime of the bi-disperse flows. Bi-dispersity determines if the flow is dominated by grain-contact or grain-inertial stresses and is characterised by Savage Number.
- b) An δ_s/δ_l tending towards unity characterises inertial flows that exerts sharp impulses, and a diminishing δ_s/δ_l characterises the progressive attenuation of these sharp impulses

by the small particles. Bi-disperse flows dominated by grain-contact stresses ($\delta_s/\delta_l < 0.26$) develop a cushioning effect to attenuate the inertia of large particles. Dynamic load upon a barrier is highly reduced upon and results in less dynamic fragmentation and impulses. On the contrary, bi-disperse flows dominated by grain-inertial stresses ($\delta_s/\delta_l > 0.26$) enhance both impulses and dynamic fragmentation.

- c) The bi-disperse flows in this study, specifically with $\delta_s/\delta_l = 0.26$ and $\delta_s/\delta_l = 0.56$, exceed the superposition of both the Hertz and hydrodynamic equation. This is because of the assumption in the hydrodynamic equation that momentum is completely destroyed upon impact. In reality, large particles will rebound and augment the resulting resisting force by the barrier. This is corroborated by back-calculated α values where an abundance of boulders were considered. This suggests that current impact models cannot capture the effects of a cluster of large particles impacting a rigid barrier. Results show that a dynamic pressure coefficient up to 5 is required to capture the sharp impulse loads induced by a cluster of large particles with diameters of up to 874 mm. Furthermore, cushioning layers are recommended for providing a practical alternative for optimising barrier designs.
- d) Dynamic fragmentation bi-disperse flows impacting a rigid barrier can be as high as 31% of the total flow energy. This suggests that fragmentation energy is enhanced due to the impact against a rigid barrier than a flexible barrier. It plays a significant role in the energy dissipation process. Test results corroborate that dynamic fragmentation is an important mechanism to consider. Considering the effects of grinding, collisions, and impact with its boundary on dynamic fragmentation would be valuable to enhancing our understanding on the impact behaviour between geophysical flows and barriers.
- e) This study fundamentally studies the effects of impact load exerted on rigid structure by both flow composition and quantities the degree of dynamic fragmentation of bi-disperse flows after intense impact. However, this conclusion is limited to apply in

practical engineering as it is technically difficult to quantify both flow composition and dynamic fragmentation of a granular flow. More research is warranted to establish an engineering approach to consider both PSD and boulders in field.

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Figure captions

Fig. 1. Centrifuge model (all dimensions are in mm): (a) side view of model setup on centrifuge platform; (b) side view of model rigid barrier

Fig. 2. Glass spheres used to model bi-disperse flows

Fig. 3. Side view of the observed kinematics and velocity fields from particle image velocimetry for bi-disperse flow ($\delta_s/\delta_l = 0.08$): (a) $t = 1.00$ s; (b) $t = 1.67$ s; (c) $t = 2.34$ s; (d) $t = 3.02$ s

Fig. 4. Side view of the observed kinematics and velocity fields from particle image velocimetry for bi-disperse flow ($\delta_s/\delta_l = 0.56$): (a) $t = 1.00$ s; (b) $t = 1.67$ s; (c) $t = 2.34$ s; (d) $t = 3.02$ s

Fig. 5. Normalised impact load time-history on rigid barrier: (a) $\delta_s/\delta_l = 0.08$; (b) $\delta_s/\delta_l = 0.26$; (c) $\delta_s/\delta_l = 0.56$

Fig. 6. Effects of grain-stresses on dynamic pressure coefficient for rigid barrier

Fig. 7. Measured particle size distributions (PSD) for rigid and flexible barrier: (a) $\delta_s/\delta_l = 0.08$; (b) $\delta_s/\delta_l = 0.26$; (c) $\delta_s/\delta_l = 0.56$

Fig. 8. Influence between Savage Number N_{Sav} and relative breakage B_R

Fig. 9. Relationship between fragmentation energy E_F and relative breakage B_R

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(a)

(b)

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Table 1. Summary of relevant centrifuge scaling laws

Parameter	Dimension	Scaling law (Model / Prototype)
Length	L	1/N
Mass	M	1/N ³
Inertia time	T	1/N
Shear strain rate	T ⁻¹	N
Velocity	LT ⁻¹	1
Acceleration	LT ⁻²	1/N
Volume	L ³	1/N ³
Density	ML ⁻³	1
Force	MLT ⁻²	1/N ²
Kinetic energy	ML ² T ⁻²	1/N ³

Table 2. Test programme and flow characterisation

Test ID	Barrier type	Model particle diameter (prototype) mm		Normalised diameter δ_s/δ_l	Flow depth h (prototype) (m)	Initial bulk density ρ_{bulk} (kg/m ³)	Flow velocity v (m/s)	Froude Number Fr	Savage Number N_{Sav}
		Large particle δ_l	Small particle δ_s						
R3	Rigid	39 (874)	3 (67)	0.08	0.05 (1.21)	1390	12.7	3.87	0.04
R10			10 (224)	0.26	0.08 (1.79)	1348	9.6	2.40	0.08
R22			22 (492)	0.56	0.11 (2.42)	1240	8.6	1.84	0.13
F3	Flexible		3 (67)	0.08	0.07 (1.49)	1390	10.5	2.88	0.02
F10			10 (224)	0.26	0.10 (2.20)	1348	12.2	2.76	0.07
F22			22 (492)	0.56	0.10 (2.28)	1240	8.8	1.96	0.16

Table 3. Mass measurement and relative breakage of particles before and after the test

Test ID		Mass before test (kg)	Mass after test (kg)	Percentage of lost mass (%)	Relative breakage B_R
R3	δ_l	6.94	6.70	3.6	0.05
	δ_s	16.20	16.17	0.2	
R10	δ_l	6.94	6.61	5.0	0.12
	δ_s	16.20	16.05	0.9	
R22	δ_l	6.94	6.07	14.3	0.28
	δ_s	16.20	16.01	1.2	
F3	δ_l	6.94	6.81	1.9	0.02
	δ_s	16.20	16.12	0.5	
F10	δ_l	6.94	6.73	3.1	0.04
	δ_s	16.20	16.12	0.5	
F22	δ_l	6.94	6.32	9.8	0.14
	δ_s	16.20	16.08	0.7	